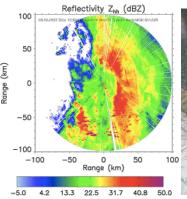




# RainGain Contracting Radar





















# Radar Specs

Type Polarimetric Doppler Weather Radar

Freq 9.3 – 9.5 Ghz

• Range 200 m − 60 Km

Resolution > 30m

Sweep rate
 Up tp 2500 Hz

Transmit Polar. Sweep to Sweep H V

Recieve Polar. Simultaneous H/V, dual channel reciever

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Transmit power <± 0.1 dB per sec, < ± 1.0 dB per day</li>

Phase noise 1° per second

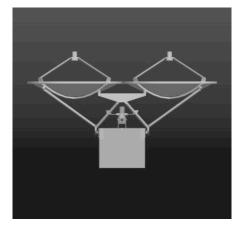
Required sens > 10 dBZ at 30Km

















High-Performance and high-reliability components From RF to Data Processing

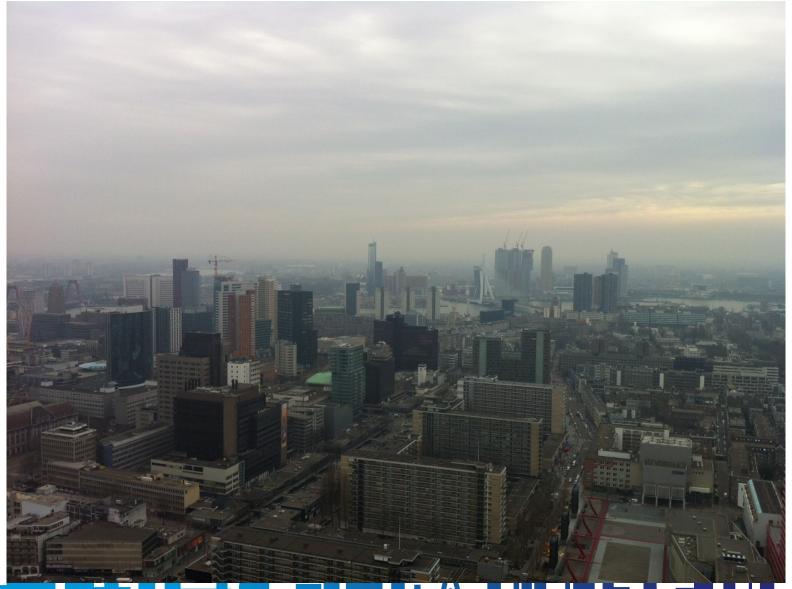
























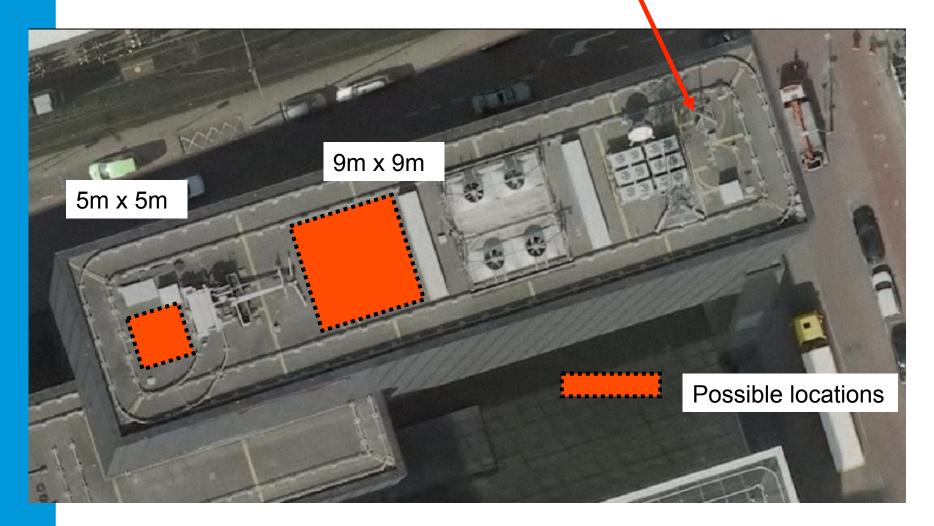




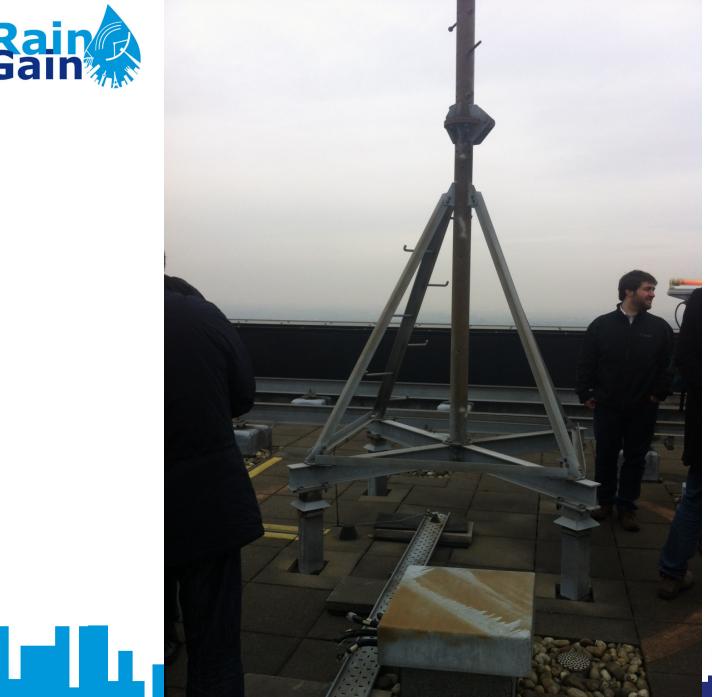














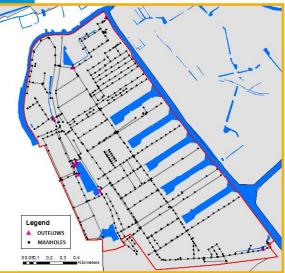




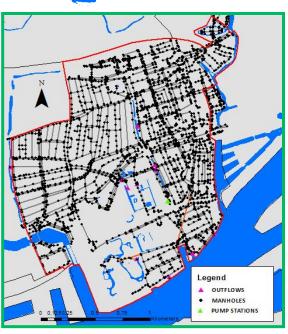
# **Rotterdam pilot locations**



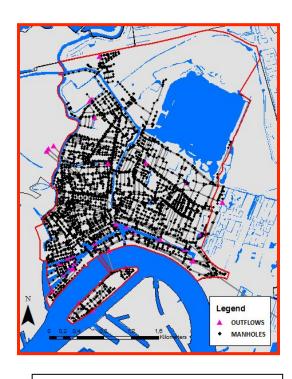




District 12. Spaanse Polder: 1,9 Km<sup>2</sup>



District 9. Centrum: 3,7 Km<sup>2</sup>



District 10. Kralingen-Crooswijk: 8 Km<sup>2</sup>



# **Urban pluvial flood mitigation options**



## 1. Underground storage

facilities (e.g. Museumpark, 10000m<sup>3</sup>)



# 3. Further optimization of system operation:

Rotterdam has a combined sewer system with 40 pumping stations that can be operated from a central control room.



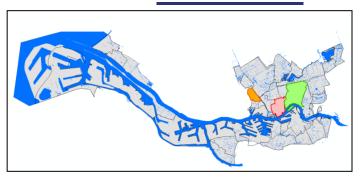
2. Water squares (e.g. Belamyplein, Benthemplein, 17000m<sup>3</sup>)

**4. Green roofs**: a durable solution for temporary water storage





# **Models**











Software: Sobek-urban 212

# **Modules:**

The **sewer system** is modelled in 1-dimension (1D) in Sobek Urban;

The **rainfall-runoff** process is modelled in Sobek RR- runoff to the sewer system is computed by delay factor +losses+infiltration module, where the discharge into the system is computed as a function of rainfall and runoff factors, which in turn depend on slope, area and type of surface.

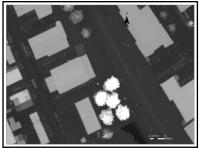
The **overland flow** will be set up using the 2-dimensional Sobek module





# **Digital Elevation Model**









The Municipality provided a set of AHN-2 layers cropped to the administrative limits of the city. This **DEM** was produced using Light Detection and Ranging (LiDAR) of ground levels from an aerial platform.

### The DEM is characterized by

- a spatial resolution of 0.5 m × 0.5 m,
- a vertical precision of 5 cm,
- a systematic error of 5 cm, a random error of 5 cm,
- a minimum precision under two standard deviations of 15 cm. [1]



# **Monitoring systems**



1. C-Band radars: De Bilt and Den Helder (200 km range, operated by KNMI) [1]

Den Helder Rotterdam area

**2. X-Band** radar: Nationale Nederlanden building, next to Central Station.



#### 3. OVER THE WHOLE URBAN AREA:

- 8 fixed rain gauges from Municipality;
- 10-15 disdrometers from TUDelft;
- 2 KNMI raingauges (Airport and Hoek van Holland);
- At least 3 manual rain gauges from amaterus.





